## Chapter 6 Basic Function Instruction

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Basic Function Instruction


- The total number of timers is 256 (T0~T255) with three different time bases, $0.01 \mathrm{~S}, 0.1 \mathrm{~S}$ and 1 S . The default number and allocation of timers is shown as below (Can be adjusted according to user's actual requirements by the "Configuration" function):

$$
\begin{aligned}
& \text { T0~T49: 0.01S timer (default as } 0.00 \sim 327.67 \mathrm{~S} \text { ) 。 } \\
& \text { T50~T199: 0.1S timer (default as } 0.0 \sim 3276.7 \mathrm{~S} \text { ) } \\
& \text { T200~T255: 1S timer (default as } 0 \sim 32767 \mathrm{~S} \text { ) }
\end{aligned}
$$

- FBs-PLC programming tool will lookup the timer's time base automatically according to the "Memory Configuration" after the timer number is keyed in. Timer's time $=$ Time base $\times$ Preset value. In the example 1 below, the time base T0 $=0.01 \mathrm{~S}$ and the PV value $=1000$, therefore the T 0 timer's time $=0.01 \mathrm{~S} \times 1000=$ 10.00S.
- If PV is a register, then Timer's time = Time base x register content. Therefore, you only need to change the register content to change the timer's time. Please refer to Example 2.
※ The maximum error of a timer is a time base plus a scan time. In order to reduce the timing error in the application, please use the timer with a smaller time base.


## Description

- When the time control "EN" is 1 , the timer will start timing (the current value will accumulate from 0 ) until "Time Up" (i.e. CV $\geqq P V$ ), then the Tn contact and TUP (FOO) will change to 1. As long as the timer control "EN" input is kept as 1, even the CV of Tn has reached or exceeded the PV, the CV of the timer will continue accumulating (with M1957 = 0) until it reaches the maximum limit (32767). The Tn contact status and flag will remain as 1 when $C V \geqq P V$, unless the " $E N$ " input is 0 . When " $E N$ " input is 0 , the $C V$ of Tn will be reset to 0 immediately and the Tn contact and "Time Up" flag TUP will also change to 0 (please refer to the diagram (1) below).
- If the FBs-PLC OS version is higher than V3.0 (inclusive), the M1957 can be set to 1 so the CV will not accumulate further after "Time Up" and stops at the PV value. The default value of the M1957 is 0, therefore the status of M1957 can be set before executing any timer instruction in the program to individually set the timer CV to continue accumulating or stop at the PV after "Time Up" (please refer to the diagram (2) below).

Basic Function Instruction



## Example 2

Variable PV

The preset value (PV) shown in example 1 is a constant which is equal to 1000 . This value is fixed and can not be changed once programmed. In many circumstances, the preset time of the timers needs to be varied while PLC running. In order to change the preset time of a timer, can first use a register as the PV operand (R or WX, WY...) and then the preset time can be varied by changing the register content. As shown in this example, if set R0 to100, then T becomes a 10S Timer, and hence if set R0 to 200, then T becomes a 20 S Timer.

Basic Function Instruction


Remark: If the preset value of the timer is equal to 0 , then the timer's contact status and FOO (TUP) become 1 ("EN" input must be at 1) immediately after the PLC finishes its first scan because "Time-Up" has occurred. (TUP) stays at 1 until "EN" input changes to 0 .

| C |  | COUNTER <br> (16-Bit: C0~C199, 32-Bit: C200~C255) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Ladder symbol Operand |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Clock -PLS -ClPV :Clear control |  |  |  |  | -CUP-Count-UP(FOO) |  |  |  | Cn : The Counter number PV: Preset value |  |  |  |  |  |
| RangeOpe-rand |  | WX | WY | WM | WS | TMR | CTR | HR | IR | OR | SR | ROR | DR | K |
|  |  | $\begin{gathered} w \times 0 \\ 1 \\ w \times 240 \end{gathered}$ | wYo । wY240 | wMo <br> \| WM1896 | $\begin{gathered} \text { wso } \\ \text { ws984 } \end{gathered}$ | $\begin{gathered} \text { TO } \\ \text { । } \\ \text { T255 } \end{gathered}$ | $\left\lvert\, \begin{gathered} \mathrm{C} 0 \\ \text { । } \\ \mathrm{C} 255 \end{gathered}\right.$ | $\begin{gathered} \text { R0 } \\ \text { I } \\ \text { R3839 } \end{gathered}$ | $\begin{gathered} \text { R3840 } \\ \text { I } \\ \text { R3903 } \end{gathered}$ | $\begin{gathered} \text { R3904 } \\ \text { । } \\ \text { R3967 } \end{gathered}$ | $\begin{gathered} \text { R3968 } \\ \text { 1 } \\ \text { R416 } \end{gathered}$ | $\begin{gathered} \text { R5000 } \\ \text { । } \\ \text { R8071 } \end{gathered}$ | $\begin{gathered} \text { D0 } \\ \text { I } \\ \text { D4095 } \end{gathered}$ | $\left\|\begin{array}{c} 0 \\ 1 \\ 2147483647 \end{array}\right\|$ |
|  | Cn |  |  |  |  |  | $\bigcirc$ |  |  |  |  |  |  |  |
|  | PV | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |

- There are total 200 16-Bit counters (C0~C199). The range of preset value is between 0~32767. C0~C139 are Retentive Counters and the CV value will be retained when the PLC turns on or RUN again after a power failure or a PLC STOP. For Non Retentive Counters, if a power failure or PLC STOP occurs, the CV value will be reset to 0 when the PLC turns on or RUN again.
- There are total 56 32-Bit counters (C200~C255). The range of the preset value is between 0~2147483647. C200~C239 are Retentive Counters and C240~C255 are Non Retentive Counters.
- The default number and assignment of the counters are shown below, if necessary can use the "CONFIGURATION" function to change the settings.
- To insure the proper counting, the sustain time of input status of CLK should greater than 1 scan time.
- The max. counting frequency with this instruction can only up to 20 Hz , for higher frequency please use the high-speed soft/hardware counter.


## Description

- When "CLR" is at 1 , all of the contact Cn, FOO (CUP), and CV value of the counter CV are cleared to 0 and the counter stops counting.
- When "CLR" is at 0 , the counter is allowed to count up. The Counter counts up every time the clock "CK $\uparrow$ " changes from 0 to 1 (adds 1 to the CV ) until the cumulative current value is equal to or greater than the preset value (CV>=PV), the counter "Count-Up" and the contact status of the counter Cn and FOO (CUP) changes to 1 . If the input status of clock continues to change, even the cumulative current value is equal and greater than the preset value, the CV value will still accumulate until it reaches the up limit at 32767 or 2147483647. The contact Cn and FOO (CUP) stay at 1 as long as CV>=PV unless the "CLR" input is set to 1. (please refer the diagram (1) below) 。
- If the FBs-PLC OS version is higher than V3.0 (inclusive), the M1973 can set to 1 so the CV will not accumulate further after "Count Up" and stops at the PV. M1973 default value is 0 , therefore the status of M1973 can be set before executing any counter instruction in the program to individually set the counter CV to continue accumulating or stops at the PV after "Count Up" (please refer to the diagram (2) below).

Basic Function Instruction


Basic Function Instruction


Remark: If the preset value of the counter is 0 and "CLR" input also at 0 , then the Cn contact status and FOO (CUP) becomes 1 immediately after the PLC finishes its first scan because the "Count-Up" has occurred. It will stay at 1 regardless how the CV value varies until "CLR" input changes to 1 .

Basic Function Instruction



Basic Function Instruction



Basic Function Instruction

| FUN 0 MC | MASTER CONTROL LOOP START |  |  | $\begin{aligned} & \text { FUN } 0 \\ & \text { MC } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: |
| Symbol |  |  |  |  |
| Ladder symbol Operand |  |  |  |  |
| $\mathrm{N}:$ Master Control Loop number ( $\mathrm{N}=0 \sim 127$ ) the number N cannot be used repeatedly. |  |  |  |  |

## Description

- There are a total of 128 MC loops ( $\mathrm{N}=0 \sim 127$ ). Every Master Control Start instruction, MC N, must correspond to a Master Control End instruction, MCE N, which has the same loop number as MC N. They must always be used in pairs and you should also make sure that the MCE N instruction is after the MC N instruction.
- When the Master Control input "EN/" is 1, then this MC N instruction will not be executed, as it does not exist.
- When the Master Control input "EN/" is 0 , the master control loop is active, the area between the MC N and MCE N is called the Master Control active loop area. All the status of OUT coils or Timers within Master Control active loop area will be cleared to 0 . Other instructions will not be executed.


## Example




Basic Function Instruction

| FUN 1 MCE | MASTER CONTROL LOOP END |  |  | FUN 1 <br> MCE |
| :---: | :---: | :---: | :---: | :---: |
| Symbol | Ladder symbol |  |  |  |
|  |  |  | N : Mast can | $0 \sim 127) N$ |
| Description |  |  |  |  |

- Every MCE N must correspond to a Master Control Start instruction. They must always be used as a pair and you should also make sure that the MCE $N$ instruction is after the MC $N$ instruction. After the MC $N$ instruction has been executed, all output coil status and timers will be cleared to 0 and no other instructions will be executed. The program execution will resume until a MCE instruction which has the same N number as MC N instruction appears.
- MCE instruction does not require an input control because the instruction itself forms a network which other instructions can not connect to it. If the MC instruction has been executed then the master control operation will be completed when the execution of the program reaches the MCE instruction. If MC N instruction has never been executed then the MCE instruction will do nothing.

Description

- Please refer to the example and explanations for MC instruction.

Basic Function Instruction


Basic Function Instruction


## Basic Function Instruction

$\left.$| FUN 3 <br> SKPE |  |  | SKIP END |
| :---: | :---: | :---: | :---: | | FUN 3 |
| :---: |
| SKPE | \right\rvert\,

- Every SKPE $N$ must correspond to a SKP $N$ instruction. They must always be used as a pair and you should also make sure that the SKPE $N$ instruction is behind the SKP N instruction.
- SKPE instruction does not require an input control because the instruction itself forms a network which other instructions can not connect to it. If the SKP $N$ instruction has been executed then the skip operation will be completed when the execution of the program reaches the SKPE $N$ instruction. If SKP $N$ instruction has never been executed then the SKPE instruction will do nothing.

Example

- Please refer to the example and explanations for SKP $N$ instruction.

Remark : SKP/SKPE instructions can be used by nesting or interleaving. The coding rules are the same as for the MC/MCE instructions. Please refer to the section of MC/MCE instructions.

Basic Function Instruction


|  | Y | M | SM | S |
| :---: | :---: | :---: | :---: | :---: |
|  | Yo | M0 | M1912 | S0 |
|  | \| | \| | \| | 1 |
|  | Y255 | M1911 | M2001 | S999 |
| D | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ * | $\bigcirc$ |

## Description

- The DIFU instruction is used to output the up differentiation of a node status (status input to "TGU") and the pulse signal resulting from the status change at the rising edge of the "TGU" for one scan time is stored to a coil specified by D.
- The functionality of this instruction can also be achieved by using a TU contact.

Example The results of the following two samples are exactly the same

| Ladder Diagram | Key Operations | Mnemonic Codes |
| :---: | :---: | :---: |
| Example 1 |  | ORG  $X$ 1 <br> FUN  4  <br>  $D:$ $Y$ 0 |
| Example 2 $\square$ YO |  | ORG TU $X$ 1 <br> OUT  $Y$ 0 |


t: scan time


Basic Function Instruction



Basic Function Instruction



Remark 1: Since the counting operation of UDCTR is implemented by software scanning, therefore if the clock speed is faster than the scan speed, lose count may then happen (generally the clock should not exceed 20 Hz depending on the size of the program). Please use the software or hardware high-speed counter in the PLC. Refer to the "High Speed Counter Application" in the Advanced Manual.

Remark 2: In order to ensure the proper counting, the sustain time of the status of clock input should greater than 1 scan time.

Basic Function Instruction

| FUN 8 DP MOV | MOVE <br> (Moves data from $S$ to $D$ ) |  |  |  |  |  |  |  |  |  |  |  |  | FUN 8 DP MOV |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Description |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\text { Move control - EN }\left\{\begin{array}{l} \text { 8DP.MOV } \\ \mathrm{S}: \\ \mathrm{D}: \end{array}\right.$ |  |  |  |  | S : Source register number <br> D : Destination register number <br> The S, N, D may combine with V, Z, P0~P9 to serve indirect addressing |  |  |  |  |  |  |  |  |  |
| Range | Wx | WY | WM | Ws | TMR | CTR | HR | IR | OR | SR | ROR | DR | K | XR |
| Operand | $\begin{gathered} \mathrm{wxo} \\ 1 \\ w \times 240 \end{gathered}$ | $\begin{array}{\|c\|} \hline \text { WYo } \\ \text { I } \\ \text { WY240 } \end{array}$ | $\begin{array}{\|c\|c\|} \hline \text { WM0 } \\ \text { । } \\ \text { WM1896 } \end{array}$ | $\begin{gathered} \text { wso } \\ \text { I } \\ \text { ws984 } \end{gathered}$ | $\begin{gathered} \hline \text { T0 } \\ \text { \| } \\ \text { T255 } \end{gathered}$ | $\begin{array}{c\|c}  & \begin{array}{c} \mathrm{Co} \\ 1 \\ \mathrm{C} 255 \end{array} \\ \hline \end{array}$ | $\begin{gathered} \hline \text { R0 } \\ \text { । } \\ \text { R3839 } \end{gathered}$ | $\begin{gathered} \hline \text { R3840 } \\ \text { I } \\ \text { R3903 } \end{gathered}$ | $\begin{gathered} \hline \text { R3904 } \\ \text { I } \\ \text { R3967 } \end{gathered}$ | $\begin{gathered} \text { R3968 } \\ \text { I } \\ \text { R4167 } \end{gathered}$ | $\begin{gathered} \text { R5000 } \\ \text { I } \\ \text { R8071 } \end{gathered}$ | $\begin{gathered} \hline \text { D0 } \\ \text { । } \\ \text { D4095 } \end{gathered}$ | $\left\|\begin{array}{c} \text { 16/32-bit } \\ +/- \text { number } \end{array}\right\|$ | $\begin{aligned} & \hline V \cdot Z \\ & P 0 \sim P 9 \end{aligned}$ |
| S | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| D |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ | $\bigcirc *$ | $\bigcirc *$ | $\bigcirc$ |  | $\bigcirc$ |
| Description |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

- Move (write) the data of $S$ to a specified register $D$ when the move control input "EN" $=1$ or from 0 to 1 ( instruction).


| Ladder Diagram | Key Operations | Mnemonic Codes |
| :---: | :---: | :---: |
| $\cdot \stackrel{\text { XO }}{ } \cdot \begin{array}{llr} \text { 8P.MOV } \\ \text { - } \\ \mathrm{D}: & & 10 \\ \text { : } & \mathrm{R} & 0 \end{array}$ |  | $\left.\begin{array}{rlrl}\text { ORG } & & \text { X } & 0 \\ \text { FUN } & & 8 \mathrm{P}\end{array}\right)$ |

S | K | 10 |
| :--- | :--- |

§ $\times 0=$ 个

D | R0 | 10 |
| :--- | :--- |

Basic Function Instruction


Basic Function Instruction


Basic Function Instruction



Basic Function Instruction


Basic Function Instruction



Basic Function Instruction



|  | $\div$ | Sa | R1 | R0 |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |
|  |  | Sb | R3 | R2 |
|  |  |  | 1234567 |  |
| D | R7 | R6 | R5 | R4 |
|  | 571634 |  | 1739 |  |
| Remainder |  |  | Quotient |  |

Basic Function Instruction


- Adds 1 to the register $D$ when the increment control input "EN" $=1$ or from 0 to 1 ( $P$ instruction). If the value of $D$ is already at the upper limit of positive number 32767 or 2147483647 , adding one to this value will change it to the lower limit of negative number -32768 or -2147483648. At the same time, the overflow flag FOO (OVF) is set to 1 .


$$
\begin{aligned}
& \text { When } V=100,0+100=100 \\
& \text { D } \\
& \begin{array}{|c|c|}
\hline \text { R100 } & 2 \\
\hline
\end{array}
\end{aligned}
$$

## Basic Function Instruction



Basic Function Instruction


- Compares the data of Sa and Sb when the compare control input "EN" $=1$ or from 0 to 1 ( $\boldsymbol{P}$ instruction). If the data of Sa is equal to Sb , then set FO0 to 1. If the data of $\mathrm{Sa}>\mathrm{Sb}$, then set FO1 to 1. If the data of $\mathrm{Sa}<\mathrm{Sb}$, then set FO2 to 1 . If the data of $\mathrm{Sa}<\mathrm{Sb}$, then set the FO2 to 1 .

- From the above example, we first assume the data of R0 is 1 and R1 is 2, and then compare the data by executing the CMP instruction. The FO0 and FO1 are set to 0 and FO2 ( $a<b$ ) is set to 1 since $a<b$.
- If you want to have the compound results, such as $\geqq \supseteq \leqq<>$ etc., please send $=$ • < and > results to relay first and then combine the result from the relays.
- M1919=0, when this command in not executed, FO0, FO1, FO2 will remain in the status at last execution.
- M1919=1, when this command in not executed, FO0, FO1, FO2 are all cleared to 0 .
- Control M1919 properly to obtain memory-holding function for functional command output.

Basic Function Instruction

| FUN 18 $\qquad$ AND | LOGICAL AND |  |  |  |  |  |  |  |  |  |  |  |  | FUN 18 <br> AND |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ange | WX | WY | WM | ws | TMR | CTR | HR | IR | OR | SR | ROR | DR | K | XR |
| Ope- <br> rand | $\begin{array}{\|c} \mathrm{w} \times 0 \\ 1 \\ \mathrm{w} \times 240 \end{array}$ | $\begin{gathered} \text { WYo } \\ \text { I } \\ \text { wY240 } \end{gathered}$ | $\begin{gathered} \hline \text { WM0 } \\ \text { । } \\ \text { WM1896 } \end{gathered}$ | $\begin{array}{\|c\|} \hline \text { Ws0 } \\ \text { । } \\ \text { ws984 } \end{array}$ | $\begin{gathered} \hline \text { T0 } \\ \text { । } \\ \text { T255 } \end{gathered}$ | $\begin{gathered} \hline \mathrm{C} 0 \\ \mathrm{I} \\ \mathrm{C} 255 \end{gathered}$ | $\begin{gathered} \mathrm{R} 0 \\ 1 \\ \mathrm{R} 3839 \end{gathered}$ | $\begin{gathered} \text { R3840 } \\ 1 \\ \text { R3903 } \end{gathered}$ | $\begin{gathered} \text { R3904 } \\ \text { I } \\ \text { R3967 } \end{gathered}$ | $\begin{gathered} \text { R3968 } \\ \text { 1 } \\ \text { R416 } \end{gathered}$ | $\begin{gathered} \text { R5000 } \\ \text { I } \end{gathered}$ | $\begin{array}{\|c\|c\|} \hline \text { D0 } \\ \text { I } \\ \text { D4095 } \end{array}$ | $\begin{array}{\|c} \text { 16/32 bit } \\ +/- \text { number } \end{array}$ | $\begin{aligned} & V \cdot z \\ & P O-P 9 \end{aligned}$ |
| Sa | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Sb | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| D |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ | $\bigcirc *$ | $\bigcirc$ * | $\bigcirc$ |  | $\bigcirc$ |

- Performs logical AND operation for the data of Sa and Sb when the operation control input "EN" $=1$ or from 0 to 1 ( $\boldsymbol{P}$ instruction). This operation compares the corresponding bits of Sa and Sb (B0~B15 or B0~B31). The bit in the $D$ is set to 1 if both of the corresponding bits data of $S a$ and $S b$ is 1 . The bit in the $D$ is set to 0 if one of the corresponding bits is 0 .


Basic Function Instruction

| $\begin{gathered} \text { FUN } 19 \text { D P } \\ \text { OR } \end{gathered}$ | LOGICAL OR |  |  |  |  |  |  |  |  |  |  |  |  | FUN 19 OR |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\text { Operation control }-\mathrm{EN}-\left[\begin{array}{l} \text { 19DP.OR- }-\left[\begin{array}{l} \text { Sa : } \\ \mathrm{Sb}: \\ \mathrm{D}: \end{array}\right] \end{array}\right.$ |  |  |  |  | - $\mathrm{D}=0$ - Result is 0 (FOO) |  |  |  | Sa: The register to be ORed <br> Sb: The register to be ORed <br> D : The register to store the result of OR The Sa, Sb, D may combine with V, Z, P0 serve indirect addressing |  |  |  |  |  |
| Range | wx | WY | WM | WS | TMR | CTR | HR | IR | OR | SR | ROR | DR | K | XR |
| Ope- <br> rand | $\begin{gathered} \mathrm{w} \times 0 \\ \mathrm{l} \\ \mathrm{w} \times 240 \end{gathered}$ | $\begin{gathered} \text { WYo } \\ \text { I } \\ \text { wY2 } \end{gathered}$ | $\begin{gathered} \hline \text { Wм0 } \\ \text { । } \\ \text { WM1896 } \end{gathered}$ | $\begin{gathered} \text { wso } \\ \text { w } \\ \text { ws984 } \end{gathered}$ | $\begin{gathered} \hline \text { T0 } \\ \text { I } \\ \text { T255 } \end{gathered}$ | $\begin{gathered} \hline \mathrm{c} 0 \\ 1 \\ \mathrm{C} 255 \end{gathered}$ | $\begin{gathered} \text { R0 } \\ \text { I } \\ \text { R3839 } \end{gathered}$ | $\begin{gathered} \text { R3840 } \\ \text { I } \\ \text { R3903 } \end{gathered}$ | $\begin{gathered} \text { R3904 } \\ \text { I } \\ \text { R3967 } \end{gathered}$ | $\begin{gathered} \text { R3968 } \\ \text { 1 } \\ \text { R4167 } \end{gathered}$ | $\begin{gathered} \text { R5000 } \\ \text { । } \\ \text { R8071 } \end{gathered}$ | $\begin{gathered} \text { D0 } \\ \text { \| } \\ \text { D4095 } \end{gathered}$ | $\left.\begin{gathered} 16 / 32 \text { bit } \\ +/- \text { number } \end{gathered} \right\rvert\,$ | $\begin{aligned} & \hline \mathrm{V} \cdot \mathrm{Z} \\ & \mathrm{P} 0 \sim \mathrm{Pg} \end{aligned}$ |
| Sa | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Sb | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| D |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ | $\bigcirc$ * | $\bigcirc$ * | $\bigcirc$ |  | $\bigcirc$ |

- Performs logical OR operation for the data of Sa and Sb when the operation control input "EN" $=1$ or from 0 to 1 ( $\mathbf{P}$ instruction). This operation compares the corresponding bits of Sa and Sb (B0~B15 or B0~B31). The bit in the D is set to 1 if one of the corresponding of Sa or Sb is 1 . The bit in the D is set to 0 if both of the corresponding bits of Sa and Sb is 0 .


Basic Function Instruction

| $\begin{gathered} \text { FUN } 20 \text { D P } \\ \rightarrow B C D \end{gathered}$ | BIN TO BCD CONVERSION <br> (Converts BIN data of the device specified at S into BCD and stores the result in D) |  |  |  |  |  |  |  |  |  |  |  |  | $\begin{array}{r} \text { FUN } 2 \\ \rightarrow B \end{array}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ladder symbol Conversion control - EN $\left\{\begin{array}{l}20 \mathrm{DP} . \rightarrow \mathrm{BCD} \\ \mathrm{S}: \\ \mathrm{D}:\end{array}\right.$ |  |  |  |  | ERR - Error (FOO) |  |  |  | S : The register to be converted <br> D : The register to store the converted da <br> (BCD code) <br> The S, D may combine with V, Z, P0~P9 indirect addressing |  |  |  |  |  |
|  | wx | WY | WM | ws | TMR | CTR | HR | IR | OR | SR | ROR | DR | K | XR |
|  | $\begin{gathered} \hline w \times 0 \\ 1 \\ w \times 240 \end{gathered}$ | $\begin{gathered} \text { WYo } \\ \text { । } \\ \text { WY240 } \end{gathered}$ | $\begin{gathered} \text { WMO } \\ \text { । } \\ \text { WM1896 } \end{gathered}$ | $\begin{gathered} \hline \text { wSO } \\ \text { । } \\ \text { ws984 } \end{gathered}$ | $\begin{array}{cc} \hline \text { T0 } \\ \text { I } \\ \text { T225 } \end{array}$ | $\begin{gathered} \hline \mathrm{C} 0 \\ \text { । } \\ \text { C255 } \end{gathered}$ | $\begin{gathered} \mathrm{R} 0 \\ 1 \\ \mathrm{R} 3839 \end{gathered}$ | $\begin{array}{\|c} \hline \text { R3840 } \\ \text { 1 } \\ \text { R3903 } \end{array}$ | $\begin{array}{\|c} \hline \mathrm{R} 3940 \\ 1 \\ \text { R3967 } \end{array}$ | $\begin{gathered} \hline \mathrm{R} 3968 \\ \mathrm{\mid} \\ \mathrm{R} 4167 \end{gathered}$ | $\begin{array}{\|c} \mathrm{R} 5000 \\ \mid \\ \mathrm{R} 8071 \end{array}$ | $\begin{array}{\|c} \text { D0 } \\ \text { I } \\ \text { D4095 } \end{array}$ | 16/32 bit +/- number | $\begin{aligned} & \hline \mathrm{V} \cdot \mathrm{Z} \\ & \mathrm{P} 0 \sim \mathrm{Pg} \\ & \hline \end{aligned}$ |
| S | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| D |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ | $\bigcirc$ * | $\bigcirc *$ | $\bigcirc$ |  | $\bigcirc$ |

- FB-PLC uses binary code to store and to execute calculations. If want to send the internal PLC data to the external displays such as seven-segment displays, it is more convenient for us to read the result on screen by converting the BIN data to BCD data. For example, it is more clear for us to read the reading "12" instead of the binary code "1100."
- Converts BIN data of the device specified at S into BCD and writes the result in D when the operation control input "EN" =1 or from 0 to 1 ( $P$ instruction). If the data in $S$ is not a BCD value (0~9999 or 0~9999999), then the error flag FOO is set to 1 and the old data of $D$ are retained.


Basic Function Instruction

| FUN 21 D P <br> $\rightarrow$ BIN | BCD TO BIN CONVERSION <br> (Converts BCD data of the device specified at S into BIN and stores the result in D) |  |  |  |  |  |  |  |  |  |  |  |  | FU |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | wx | WY | WM | ws | TMR | CTR | HR | IR | OR | SR | ROR | DR | XR |
|  |  | $\begin{gathered} \mathrm{w} \times 0 \\ 1 \\ \mathrm{w} \times 240 \end{gathered}$ | $\begin{gathered} \text { WYo } \\ 1 \\ \text { wY240 } \end{gathered}$ | $\begin{array}{\|c\|} \hline \text { Wмо } \\ \text { । } \\ \text { WM1896 } \\ \hline \end{array}$ | $\begin{gathered} \hline \text { wso } \\ \text { । } \\ \text { ws984 } \end{gathered}$ | $\begin{gathered} \hline \text { T0 } \\ \text { । } \\ \text { T255 } \end{gathered}$ | $\begin{gathered} \mathrm{c} 0 \\ \mathrm{I} \\ \mathrm{C} 255 \end{gathered}$ | $\begin{gathered} \text { R0 } \\ \text { । } \\ \text { R3839 } \end{gathered}$ | $\begin{gathered} \text { R3840 } \\ \text { I } \\ \text { R3903 } \end{gathered}$ | $\begin{gathered} \text { R3904 } \\ \text { । } \\ \text { R3967 } \end{gathered}$ | $\begin{gathered} \text { R3968 } \\ \text { । } \\ \text { R4167 } \end{gathered}$ | $\begin{gathered} \text { R5000 } \\ \text { । } \\ \text { R8071 } \end{gathered}$ | $\begin{array}{\|c} \hline \text { D0 } \\ \text { I } \\ \text { D4095 } \end{array}$ | $\begin{aligned} & V \cdot z \\ & P O \sim P 9 \\ & \hline \end{aligned}$ |
|  | S | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  | D |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ | $\bigcirc$ * | $\bigcirc *$ | $\bigcirc$ | $\bigcirc$ |

- The decimal (BCD) data must be converted to binary (BIN) data first in order for PLC to accept the data which is originally in decimal unit (BCD code) inputted from external device such as digital switch because the BCD data can not be accepted by PLC for its operations.
- Converts BCD data of the device specified at $S$ into $B I N$ and writes the result in $D$ when the operation control input "EN" =1 or from 0 to 1 ( $\mathbf{P}$ instruction). If the data in $S$ is not in BCD, then the error flag FOO is set to 1 and the old data of $D$ are retained.
- Constant is converted to BIN automatically when store in program and can not be used as a source operand of this function.


